



Status of IGS Core Products

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Abstract

The International GNSS Service (IGS) generally aims to provide ~ 1 cm satellite orbits and ~ 1 mm terrestrial frame products to meet the most demanding user needs. While the goal has not yet been met, the IGS has made good progress. The current Global Positioning System (GPS) Final orbits have accuracies better than 2.5 cm; the Rapidis are of similar quality; and the near real-time parts of the Ultra-rapids have an accuracy of ~ 3.0 cm, while the real-time parts have an accuracy of about 5 cm. About half of the total error in the GPS orbits can be attributed to systematic time-varying rotational misalignment of the orbital frames; the other half is dominated by errors in the model for sub-daily tidal variations in Earth orientation. Near-field multi-path errors, anthropogenic changes at tracking stations, and the presence of uncalibrated GNSS antenna radomes at multi-technique sites continue to be a significant source of error. While recent model and analysis changes have reduced some errors, others will remain for the foreseeable future. This paper summarizes the quality state of the IGS core products since the switch to daily terrestrial reference frame integrations (Aug. 2012), and as preparations for the next reprocessing campaign continue.

IGS Core Product Series

Series	ID	Latency	Issue times (UTC)	Data spans (UTC)	Remarks
Ultra-Rapid (predicted half)	IGU	real-time	@ 03:00, 09:00, 15:00, 21:00	+24 hr @ 00:00, 06:00, 12:00, 18:00	• for real-time apps • GPS & GLONASS • issued with prior IGA
Ultra-Rapid (observed half)	IGA	3 - 9 hr (near real-time)	@ 03:00, 09:00, 15:00, 21:00	-24 hr @ 00:00, 06:00, 12:00, 18:00	• for near-real-time apps • GPS & GLONASS • issued with following IGU
Rapid	IGR	17 - 41 hr	@ 17:00 daily	± 12 hr @ 12:00	• for near-definitive, rapid apps • GPS only
Final	IGS	12 - 19 d	weekly each Thursday	± 12 hr @ 12:00 for 7 d	• for definitive apps • GPS & GLONASS

Analysis Center Contributions

Table focuses on GPS; all GLO-only (*) and GNSS AC (*) products are included in GLO combinations.

Cen	Name	Final (IGS)			Rapid (IGR)			Ultra (IGU)			
		SP3	ERP	SNX	CLK	SP3	ERP	CLK	SP3	ERP	CLK
cod*	Centre for Orbit Determination in Europe, Bern, CHE	✓	✓	✓	✓	✓	✓	✓	✓	✓	brd
emr*	Natural Resources Canada, Ottawa, CAN	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
eso*	European Space Agency, Darmstadt, DEU	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
gfz*	GeoForschungsZentrum, Potsdam, DEU	✓	✓	✓	✓	✓	✓	✓	✓	✓	brd
gop	Geodetic Observatory Pecny, CZE	✓	✓	✓	✓	✓	✓	✓	✓	✓	✓
grg*	CNES Groupe de Recherche de Geodesie Spatiale, Toulouse, FRA	✓	✓	✓	✓						
iac*	Information and Analysis Center of Navigation, Korolyov, RUS	✓	✓	✓	✓						
jpl	Jet Propulsion Laboratory, Pasadena, USA	✓	✓	✓	✓	✓	✓	✓	✓	✓	
mit	Massachusetts Institute of Technology, Boston, USA	✓	✓	✓	✓						
nsg	National Geodetic Survey, Silver Spring, USA	✓	✓	✓	brd	✓	✓	✓	✓	✓	brd
sio	Scripps Institution of Oceanography, La Jolla, USA	✓	✓	✓	✓	✓	✓	✓	✓	✓	
usn	U.S. Naval Observatory, Washington, USA					✓	✓	✓	✓	✓	
whu*	Wuhan University, Wuhan, CHN					✓	✓	✓	✓	✓	

✓ = AC included ✓ = AC partially included ✓ = AC excluded brd = excl. brdc clock empty = none

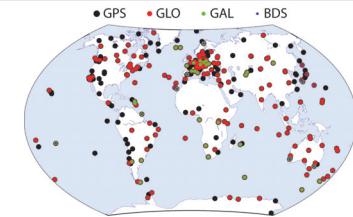
Accuracy of Core IGS Products

The table below was presented at the EGU General Assembly in 2012 [Ray and Griffiths, 2012]. It represents a best effort to quantify the accuracy of IGS products from: combination statistics and PPP analysis results (<http://acc.igs.org/>); spectral analyses of station position time series [Ray, 2006; Collilieux et al., 2007; Ray et al., 2008; Ray et al., 2013]; spectral analyses of midnight GPS orbit jumps [Griffiths and Ray, 2009; Griffiths and Ray, 2013] and midnight discontinuities in ERPs [Ray and Griffiths, 2011]; along with comparisons to loading models [Ray et al., 2011]. Very little has changed since EGU 2012, with exception to improvements in the rotational alignment of Final GPS orbits to the IGS terrestrial frame (IGb08) due to refined combination procedures.

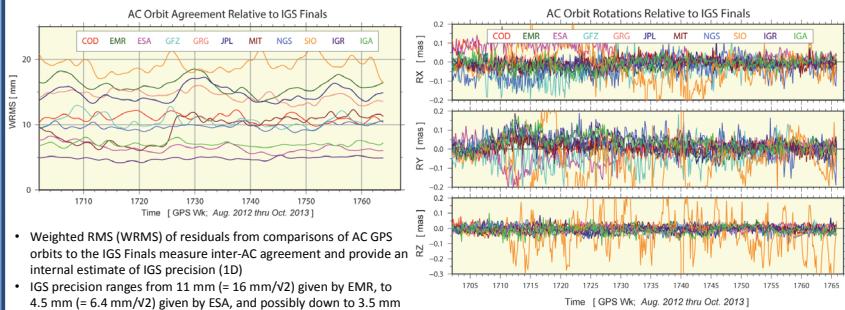
Series	Product Types	Accuracies	Output Intervals
Ultra-Rapid (predicted half)	GPS orbits	~ 5 cm (1D)	15 min
	GLONASS orbits	~ 10 cm (1D)	15 min
	GPS SV clocks	<3 ns RMS / ~ 1.5 ns Sdev	15 min
	ERPs: PM + dLOD	<250 μ s / ~ 50 μ s	6 hr
Ultra-Rapid (observed half)	GPS orbits	~ 3 cm (1D)	15 min
	GLONASS orbits	~ 5 cm (1D)	15 min
	GPS SV clocks	<15 ps RMS / ~ 50 ps Sdev	15 min
	ERPs: PM + dLOD	<50 μ s / ~ 10 μ s	6 hr
Rapid	GPS orbits	~ 2.5 cm (1D)	15 min
	GPS SV & station clocks	<75 ps RMS / ~ 25 ps Sdev	5 min
	ERPs: PM + dLOD	<40 μ s / ~ 10 μ s	daily
Final	GPS orbits	<2.5 cm (1D)	15 min
	GLONASS orbits	<5 cm (1D)	15 min
	GPS SV & station clocks	<75 ps RMS / ~ 20 ps SDev	30 s (SVs) + 5 min
	Terrestrial frames	<30 μ s / ~ 10 μ s	daily

IGS Tracking Stations Used in Latest Products

- IGS network currently consists of ~ 430 GNSS stations distributed globally, with relatively dense coverage in Europe
- 92 IGS stations (current & former) are co-located with VLBI, SLR and/or DORIS, which is an important contribution to ITRF
- Antennas at 30.4% of co-located stations are covered with uncalibrated radomes—see poster [G13B-0946](#) for efforts to mitigate effects at some stations
- ACs use data from ~ 326 IGS stations—as shown in plot to right—for their GPS and GLONASS contributions to Finals combinations (Wk 1765)
- The other ~ 145 stations used by the ACs (again, Finals GPS Wk 1765) are from regional networks (not shown)



Latest Results from the Orbit Combinations



- Weighted RMS (WRMS) of residuals from comparisons of AC GPS orbits to the IGS Finals measure inter-Ac agreement and provide an internal estimate of IGS precision (1D)
- IGS precision ranges from 11 mm (± 16 mm/V2) given by EMR, to 4.5 mm (± 6.4 mm/V2) given by ESA, and possibly down to 3.5 mm (± 5 mm/V2) given by IGR
- Time-varying rotations (see plot to the right) of orbit frames are small, but significant—dominated by ESA issues before Wk 1730

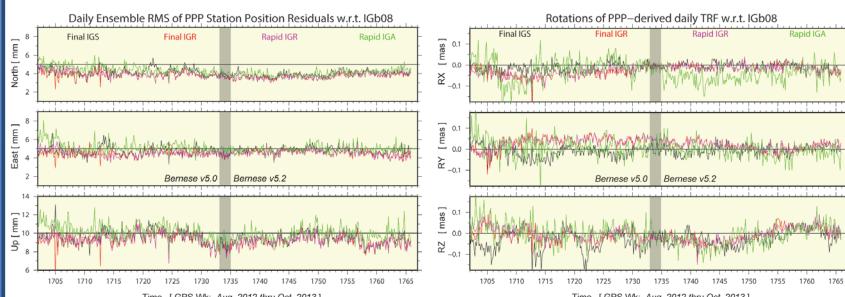
$$RX_{(IGS-IGR)/2} = -9.2 \pm 62.2 \mu\text{as}, \text{ or } -1.2 \pm 8.1 \text{ mm shift @ GPS}$$

$$RY_{(IGS-IGR)/2} = -20.5 \pm 73.5 \mu\text{as}, \text{ or } -2.7 \pm 9.5 \text{ mm shift @ GPS}$$

$$RZ_{(IGS-IGR)/2} = 14.8 \pm 55.9 \mu\text{as}, \text{ or } -1.9 \pm 7.3 \text{ mm shift @ GPS}$$

Performance of Latest Products Using PPP

Large majority (>80%) of users rely on combined satellite orbits and clocks. To monitor the quality of these products, a PPP analysis is performed as part of the routine Final and Rapid combinations for the IGS, IGR and IGA series (http://acc.igs.org/index_igsac_ppp.html). Similarity comparisons between each series' network of PPP-derived station positions and IGb08 give important insight into the quality of the combined products.



- ~ 180 D TR feature (IGR & IGS) predominantly from EMR, JPL & MIT
- Mean RX, RY, RZ offsets (below) due to misalignment of orbital frames

Series	North (mm)	East (mm)	Up (mm)
Final IGS	4.1 ± 0.4	4.8 ± 0.4	9.5 ± 0.7
Final IGR	3.8 ± 0.3	4.5 ± 0.4	9.3 ± 0.7
Rapid IGR	3.8 ± 0.4	4.5 ± 0.4	9.3 ± 0.6
Rapid IGA	4.3 ± 0.5	5.1 ± 0.6	10 ± 0.8

1 μ s = ~ 0.03 mm shift @ Earth surface

Preparations for 2nd Reprocessing (Repro2)

Preparations are underway to reanalyze the full-history of GPS (and maybe GLONASS) data using the latest analysis models and methodologies. The expected outcome is a set of homogeneous reprocessed IGS solutions for:

- daily GPS & GLO orbits & GPS satellite clocks in SP3 format
- daily GPS satellite & tracking station clocks (5m & 30s) in CLK RINEX format
- daily ERPs from SINEX (official product) & classic orbit combinations (for comparison only)
- terrestrial coordinate frames with ERPs, with
 - full variance-covariance matrix and Z-offset parameters for satellite antennas

Repro2 results are intended for inclusion in ITRF2013, and to support advancements in Earth science research and other applications of high-precision GNSS. Details about repro2 analysis standards are available at: <http://acc.igs.org/reprocess2.html>.