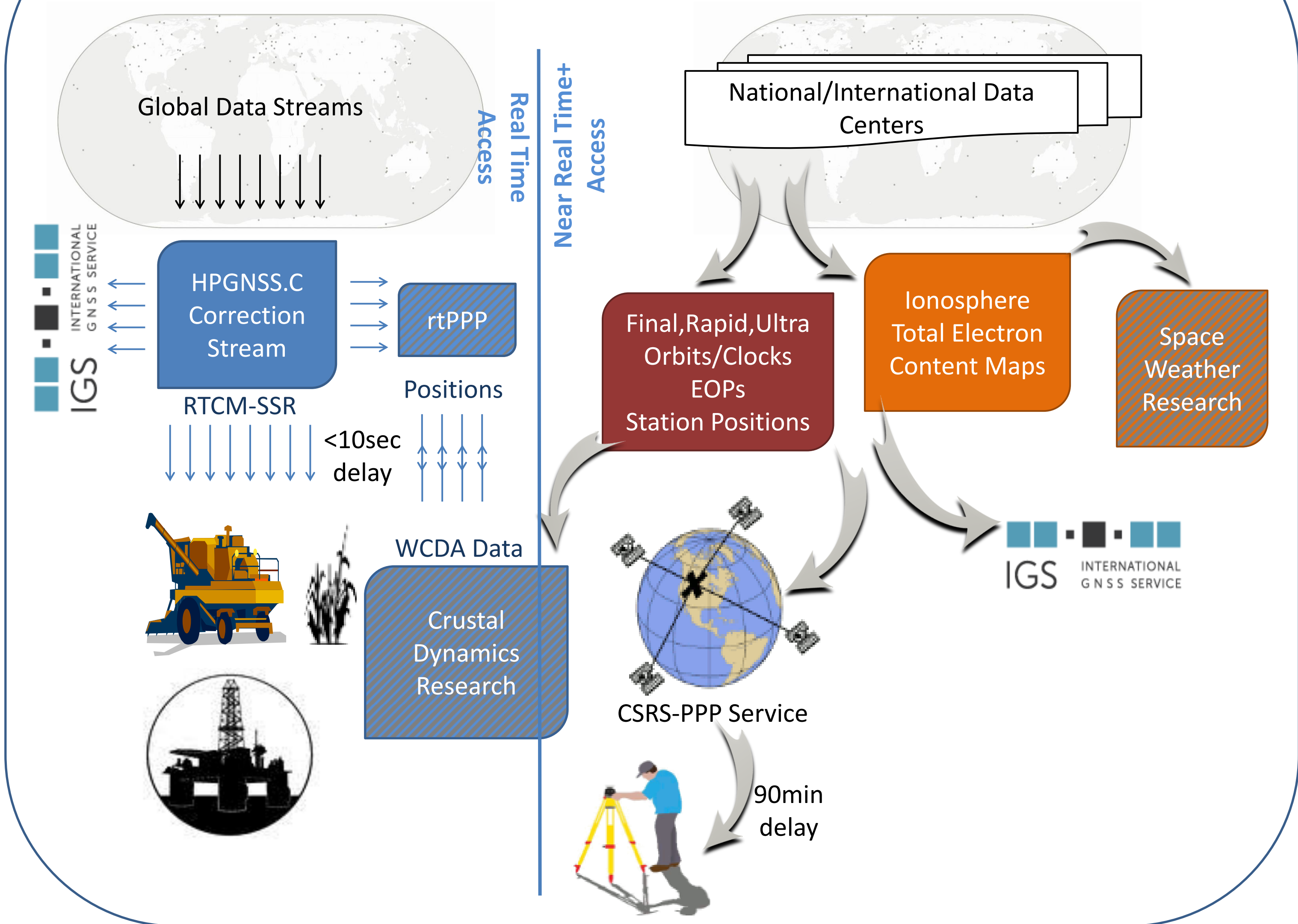


# NRCan Analysis Center Activities

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Abstract: The NRCan Analysis Center generates products (labeled em\*) for IGS, as it has been since the initial pilot project in 1992. The full complement of products are described along with recent activities and changes to the NRCan station network. A modification of the Clock-RINEX data format to accommodate time-varying instrument delays is also proposed.

## Product Generation Processes



## NRCan GPS and GLONASS Products

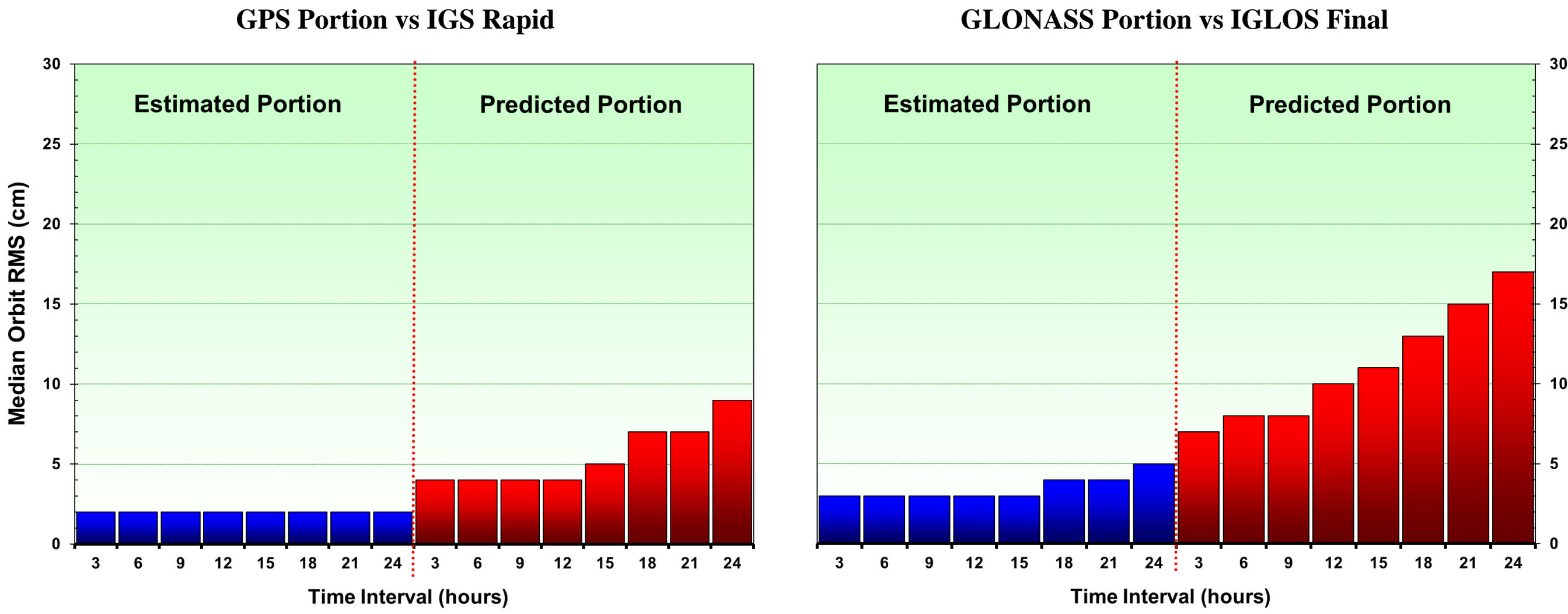
Type	Product Characteristics
Final (weekly)	<ul style="list-style-type: none"><li>➤ <b>GPS only</b><ul style="list-style-type: none"><li>Since 1994 and ongoing</li><li>Use of JPL's GIPSY-OASIS II v6.3</li><li>Daily Orbits, 30-sec clocks, ERP and SINEX</li><li>Weekly submission for IGS Final combination</li></ul></li><li>➤ <b>GPS+GLONASS</b><ul style="list-style-type: none"><li>Since 2011-Sep-11 and ongoing</li><li>Use of Bernese 5.2</li><li>Daily Orbits, 30-sec clocks and ERP</li><li>Weekly submission for IGLOS Final combination</li><li>For the time being, station XYZ are constrained as in our Rapid solutions</li></ul></li></ul>
Rapid (daily)	<ul style="list-style-type: none"><li>➤ <b>GPS+GLONASS</b><ul style="list-style-type: none"><li>Since 2011-May-22 (GPS-only solutions, using GIPSY, started in 1994 and was discontinued on 2011-May-21)</li><li>Use of Bernese 5.2</li><li>Daily Orbits, 30-sec clocks and ERP</li><li>Daily submission for IGR combination</li></ul></li></ul>
Ultra-Rapid (hourly)	<ul style="list-style-type: none"><li>➤ <b>GPS+GLONASS</b><ul style="list-style-type: none"><li>Since 2013-Sep-13, hr 12</li><li>Use of Bernese 5.2</li><li>Orbits and ERP (<b>every hour!</b>)</li><li>30-sec clocks (every 3 hours)</li><li>30-sec GPS-only clocks (every other hours)</li><li>Submission for IGU/IGV combination (4 times daily)</li></ul></li></ul>

## Precision of NRCan Products for 2015

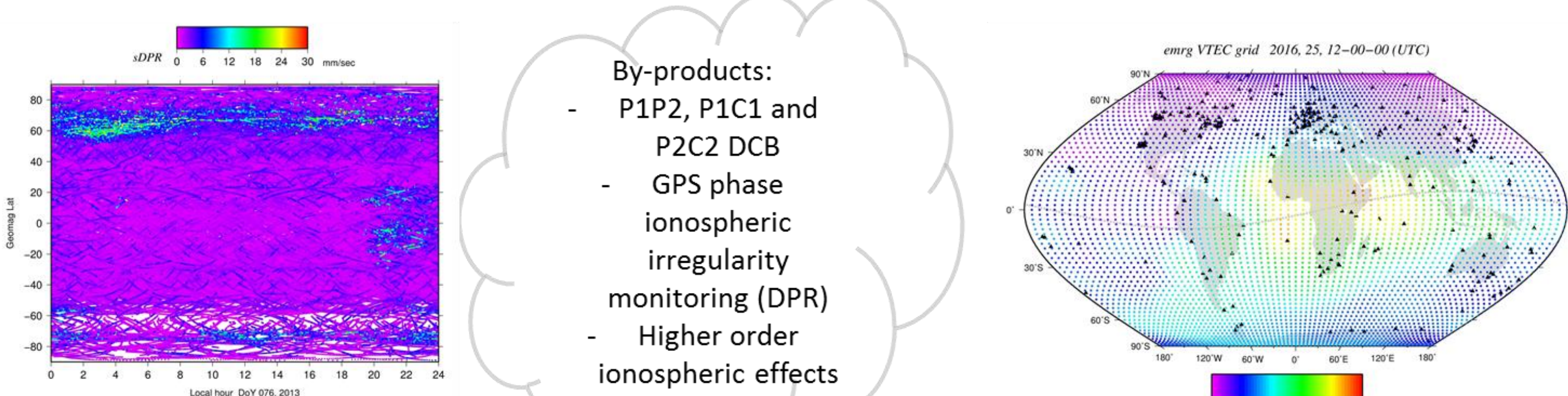
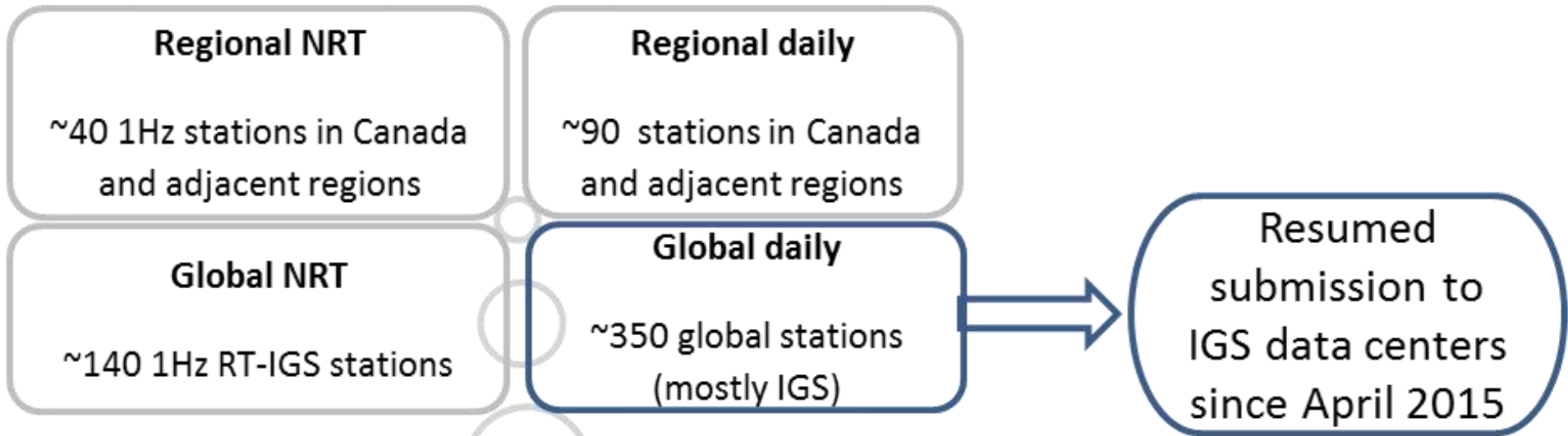
Product	Orbits <sup>(1)</sup> (cm)		Clocks <sup>(2)</sup> (ns)	
	GPS	GLONASS	GPS	GLONASS
EMU estimated (00-24h) <sup>(3)</sup>	2	3+	0.08	0.08 <sup>(4)</sup>
EMU predicted <sup>(3)</sup>	00-03 h	4	7	Not meaningful
	03-06 h	4	8	
	09-12 h	4	10	
	21-24 h	9	17	
EMR Rapid and Final <sup>(3)</sup>	2.0	4.0	0.08	0.08 <sup>(4)</sup>

(1) Orbit RMS after applying a 7-parameter Helmert transformation.  
(2) Clock RMS after proper clock alignment.  
(3) Comparison against IGR for GPS and IGL for GLONASS.  
(4) Comparison against ESA Final products after proper clock alignment and individual satellite bias removal.

### NRCan Ultra-Rapid (EMU) GPS+GLONASS Orbit Results



## Ionospheric products

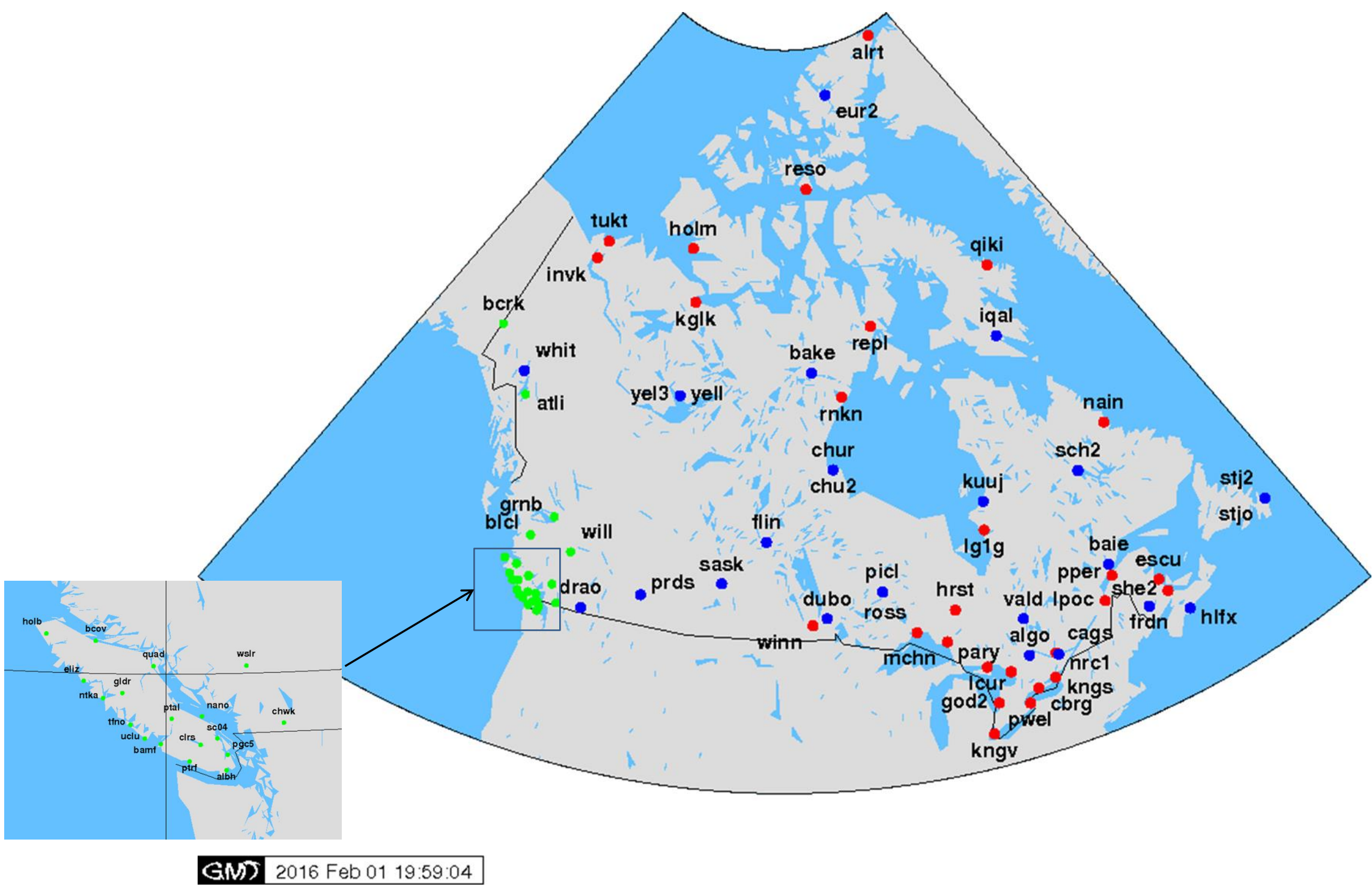


By-products:

- P1P2, P1C1 and P2C2 DCB
- GPS phase ionospheric irregularity monitoring (DPR)
- Higher order ionospheric effects

## NRCan GNSS Network

The current NRCan public GNSS network consists of 21 core stations (blue) operated by the Canadian Geodetic Survey (CGS), 27 regional stations (red) operated by CGS, as well as 24 regional sites (green) operated by the Geological Survey of Canada (GSC). Several of the most important sites including algo, chur, drao, prds, stjo, and yell have multiple monuments in order to monitor the stability of the monument and the data quality.



## Proposed Extended Clock-RINEX Format

Precise Point Positioning with Ambiguity Resolution (PPP-AR) requires precise corrections for all system equipment delays. Unique delays can exist on all signals (code and phase) and may not be constant. The most general solution then is to treat the equipment delays in the same manner as the clock errors. Hence, it is proposed to extend the current Clock-RINEX format to provide time-constant equipment delay biases and time-varying equipment delay signals time-tagged with the clock errors. At the same time, other physical corrections that directly affect the phase can be provided (e.g. the antenna orientation yaw angle).

