



GLONASS Inter-Frequency Bias and PPP Ambiguity Resolution across Inhomogeneous Receivers

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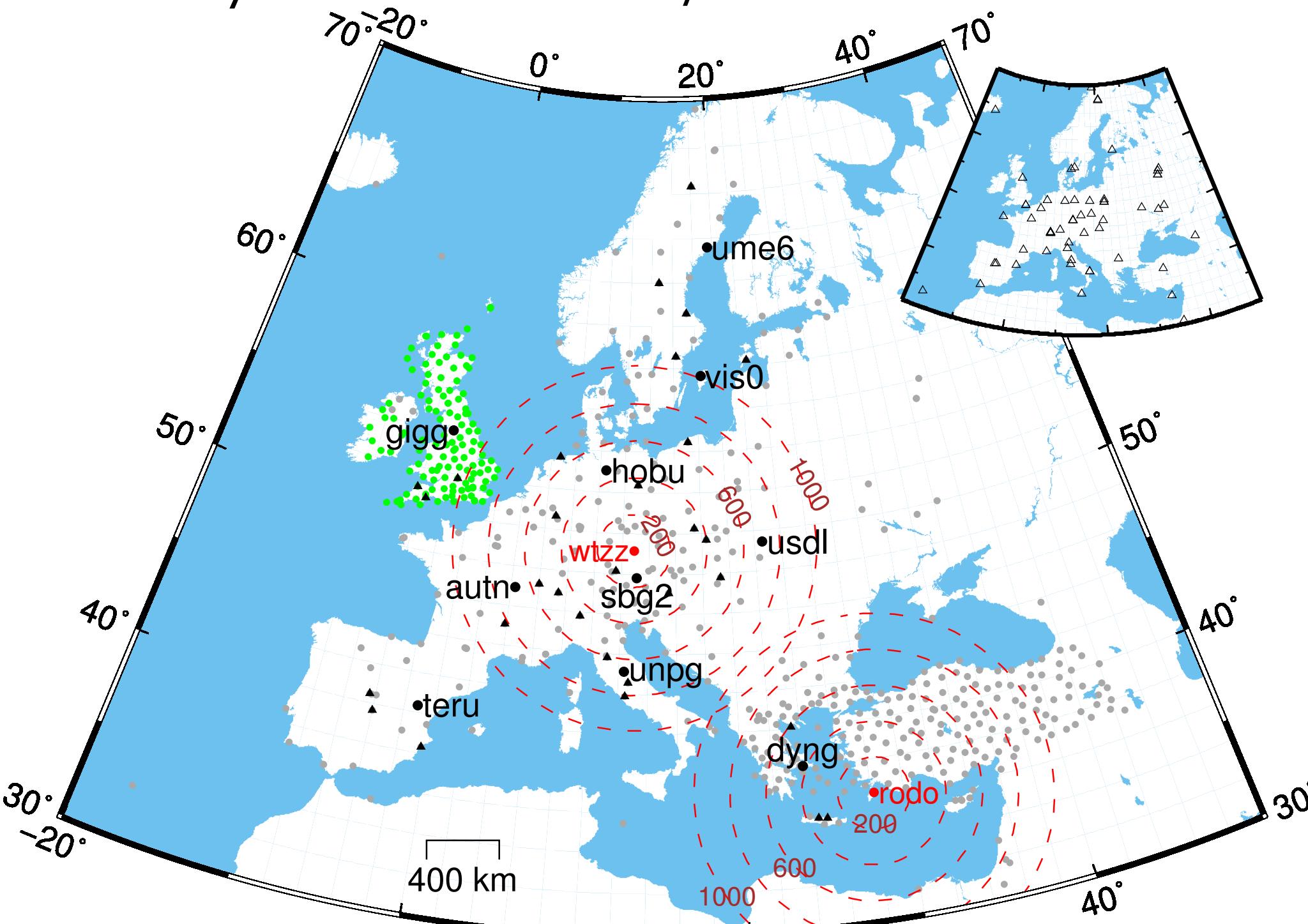


Abstract

- GLONASS PPP ambiguity resolution (PPP-AR) is difficult because
 - ① Satellites do not share the same frequencies;
 - ② Pseudorange inter-frequency biases (IFBs) vary with manufacturers, antennas, etc. which complicates PPP-AR over diverse receivers.
- We propose introducing ionosphere data to enable PPP-AR, and validate it using 550 Europe sites and global ionosphere maps (GIMs).
- Hourly PPP-AR can reach comparable performance to GPS PPP-AR.
- GIMs have a modest accuracy of only 2-8 TECU in vertical which confines PPP-AR to an approximately 800x800 km area in Europe.
- Details in "GLONASS fractional-cycle bias estimation across inhomogeneous receivers for PPP ambiguity resolution". JoG (online)

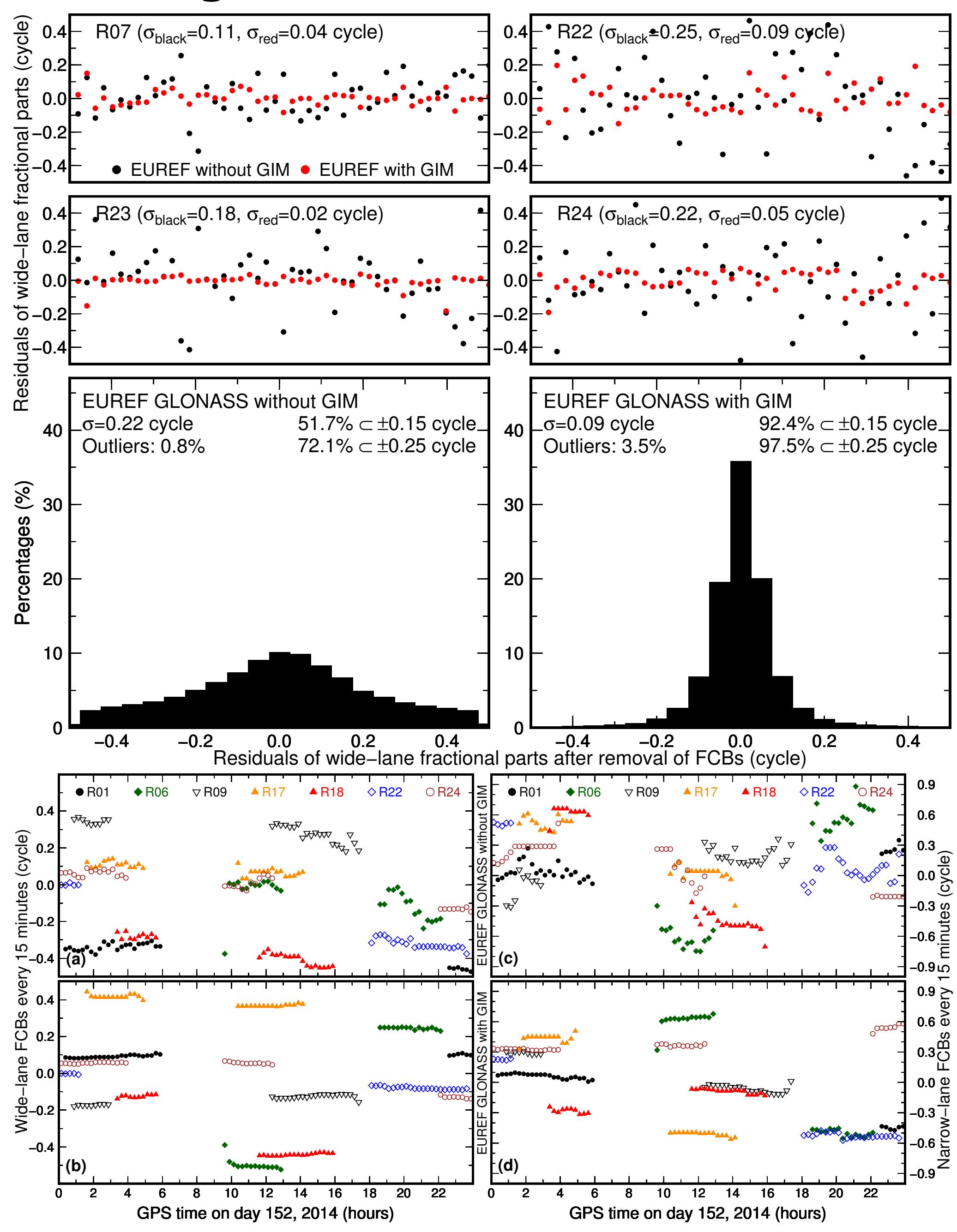
Data and validation items

- Inhomogeneous receivers (centered on WTZZ, ~800x800 km);
- Homogeneous receivers (BIGF sites in the UK, ~800x1000 km);
- To what network extent can GIMs stay effective?
- Hourly static GLONASS/GPS PPP-AR.



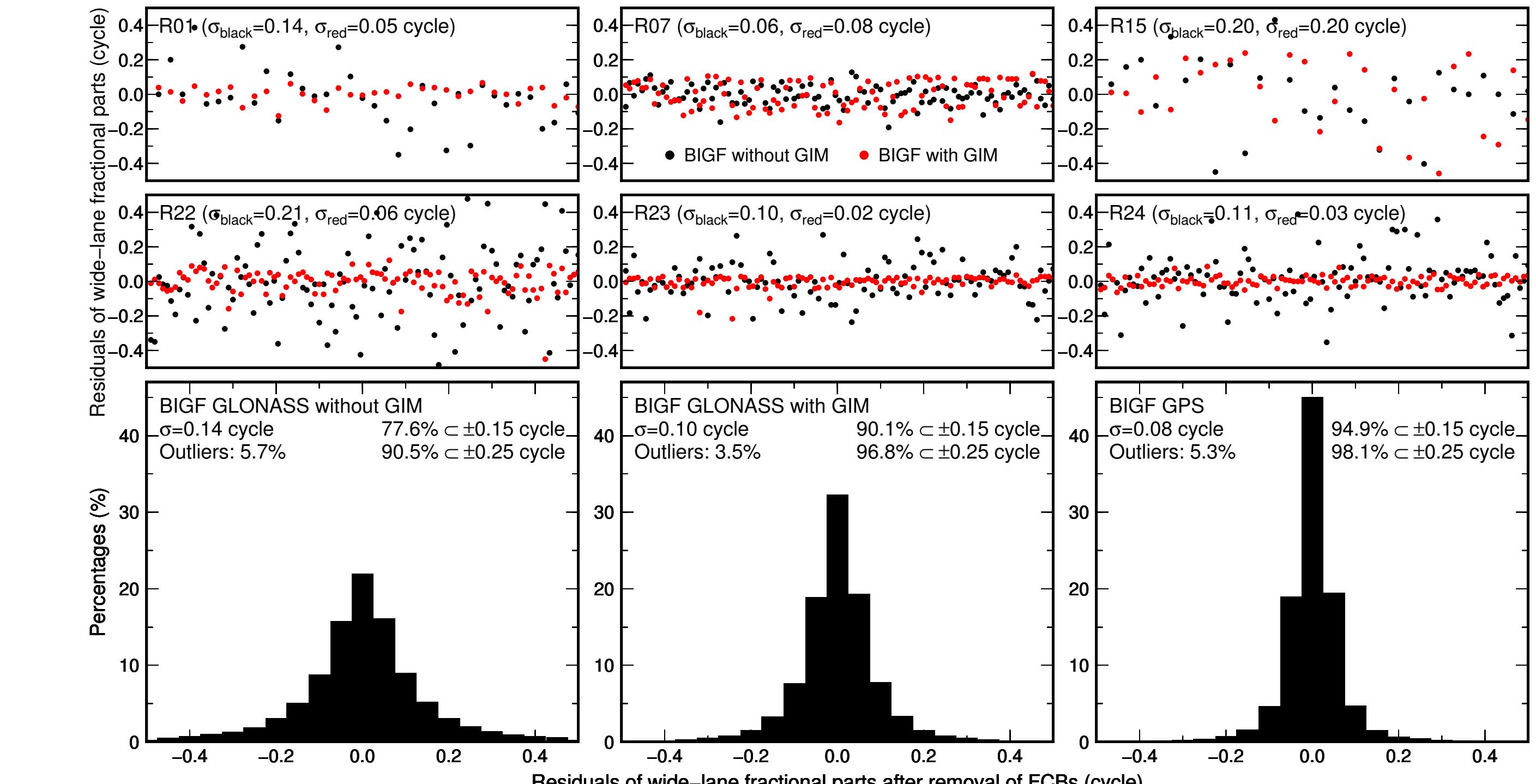
- ✓ In total 550 sites;
- ✓ 105 BIGF sites (green dots) with identical receivers;
- ✓ Concentric circles indicate areas to test GIMs;
- ✓ 40 sites (black) to test PPP-AR;
- ✓ Inset shows sites that are part of CODE sites used for GIM estimation.

Inhomogeneous receivers



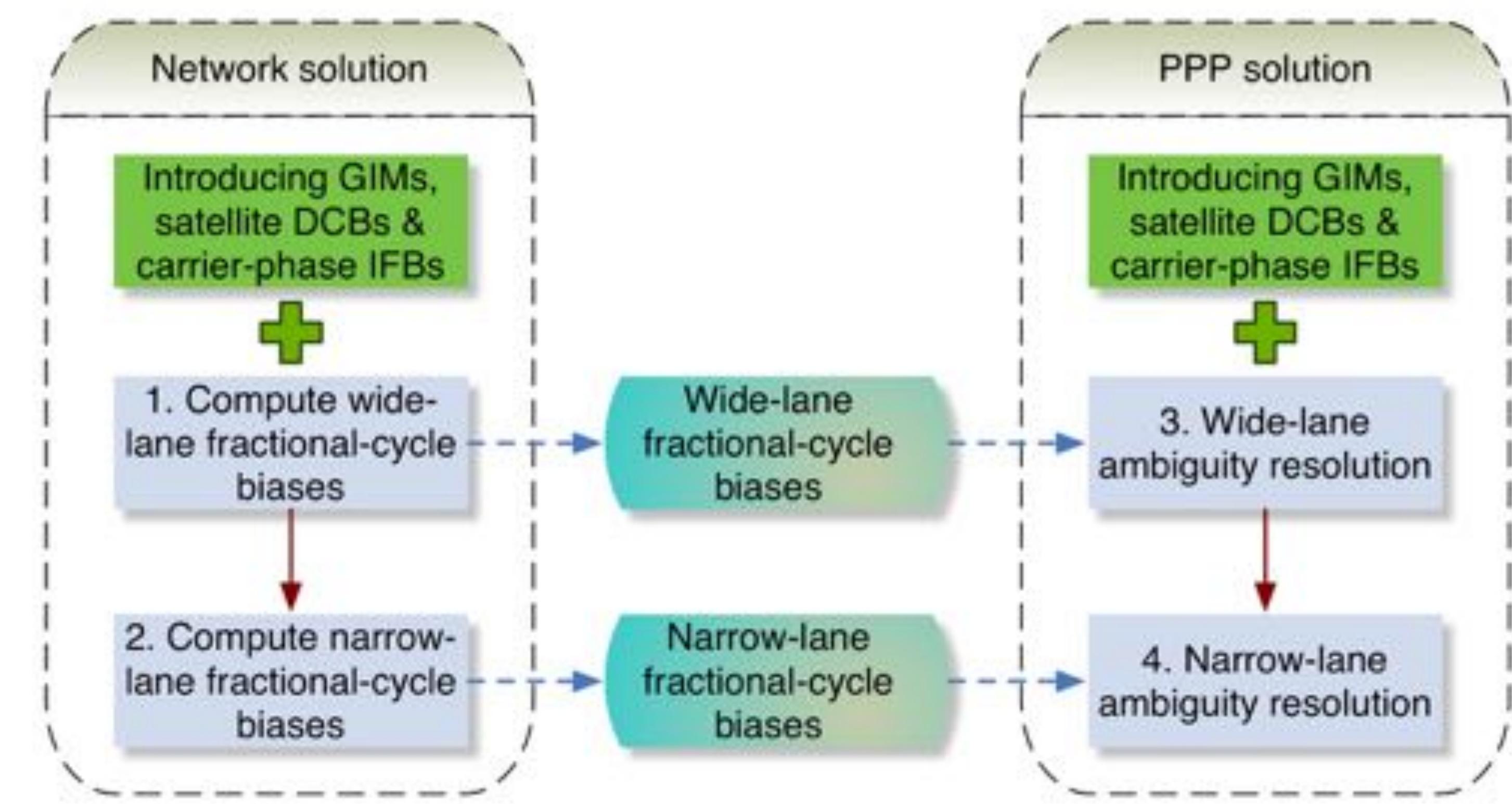
- Introducing GIMs reduces the scatter of wide-lane fractional parts;
- Wide-lane fractional parts agree well with each other within ±0.15 cycles and ensure high-quality FCBs;
- Temporal stability of wide-lane and narrow-lane FCBs are well recovered;
- Some jumps relate to low elevations and poor GIM accuracy.

Homogeneous receivers



Method description

- PPP-AR depends on the integer resolution of wide-lane ambiguities, which is achieved through Melbourne-Wübbena combination.
- However, GLONASS pseudorange are contaminated by inter-frequency biases (IFBs) that are hard to model and cannot be removed by differencing between satellites.
- So our method is
 - ① Introduce GIMs and tune the relative weights between GIMs and pseudorange data in PPP;
 - ② Correct for satellite DCBs (Differential Code Biases), but estimate receiver DCBs;
 - ③ Correct for carrier-phase IFBs in both wide-lane and narrow-lane



To what network extent can GIMs stay effective?

Effectiveness is degraded when areas become larger.

| Radii (km) | ≤0.15 cycles | ≤0.25 cycles | Outlier | σ (cycles) |
|------------|--------------|--------------|---------|------------|
| WTZZ | 96.7% | 98.9% | 1.7% | 0.06 |
| WTZZ | 92.4% | 97.5% | 3.5% | 0.09 |
| WTZZ | 89.0% | 96.6% | 3.1% | 0.10 |
| WTZZ | 85.7% | 95.4% | 3.4% | 0.11 |
| WTZZ | 83.2% | 94.0% | 4.4% | 0.12 |
| RODO | 94.2% | 98.4% | 0.0% | 0.08 |
| RODO | 83.7% | 94.4% | 1.7% | 0.12 |
| RODO | 77.1% | 91.3% | 3.4% | 0.14 |
| RODO | 74.4% | 90.0% | 3.8% | 0.15 |
| RODO | 72.4% | 88.8% | 4.3% | 0.15 |

Hourly static GLONASS PPP-AR

Comparable to GPS in positioning accuracy, but fixing rate is lower.

| Sites | Number | Outlier | East | North | Up | Fixed amb. |
|-------------------------------|-----------|---------|---------|---------|---------|------------|
| <i>GLONASS-only solutions</i> | | | | | | |
| UME6 | 2259/2856 | 0.7% | 1.4/0.6 | 1.1/0.8 | 2.2/2.0 | 60.0% |
| VISO | 2281/2843 | 0.9% | 1.9/0.7 | 1.2/0.9 | 2.3/2.1 | 65.7% |
| GIGG | 1919/2874 | 0.7% | 2.4/0.6 | 1.3/0.7 | 2.6/1.9 | 63.8% |
| HOBU | 2224/2871 | 0.4% | 2.1/0.5 | 1.3/0.7 | 2.6/1.8 | 71.5% |
| USDL | 1967/2752 | 0.1% | 2.4/0.7 | 1.3/0.6 | 2.9/1.9 | 69.5% |
| SBG2 | 1949/2844 | 1.1% | 2.7/0.6 | 1.4/0.9 | 3.7/2.5 | 67.4% |
| AUTN | 1970/2819 | 1.0% | 2.6/0.6 | 1.4/0.7 | 3.4/2.3 | 67.8% |
| UNPG | 1217/2863 | 3.2% | 3.2/1.1 | 1.7/1.3 | 4.1/3.5 | 45.3% |
| TERU | 1341/2832 | 4.7% | 3.2/0.7 | 1.6/0.9 | 4.4/3.1 | 52.2% |
| DYNG | 594/2575 | 8.4% | 3.6/0.7 | 1.7/1.2 | 4.4/3.6 | 34.9% |
| <i>GPS-only solutions</i> | | | | | | |
| UME6 | 2846/2856 | 0.4% | 1.9/0.4 | 1.3/0.5 | 2.3/1.8 | 97.0% |
| VISO | 2790/2845 | 0.6% | 2.8/0.5 | 1.5/0.6 | 2.7/1.8 | 94.3% |
| GIGG | 2614/2874 | 0.5% | 3.0/0.5 | 1.6/0.6 | 3.4/2.1 | 84.8% |
| HOBU | 2811/2871 | 1.0% | 2.7/0.5 | 1.5/0.7 | 2.8/2.3 | 93.1% |
| USDL | 2735/2756 | 0.5% | 2.9/0.6 | 1.6/0.6 | 3.4/1.8 | 97.9% |
| SBG2 | 2797/2844 | 1.3% | 3.3/0.5 | 1.7/0.7 | 3.9/2.0 | 96.5% |
| AUTN | 2739/2819 | 0.8% | 2.9/0.5 | 1.6/0.6 | 3.7/1.8 | 96.1% |
| UNPG | 2735/2866 | 3.0% | 3.9/0.6 | 2.1/0.8 | 5.0/2.4 | 92.2% |
| TERU | 2661/2832 | 2.2% | 3.4/0.6 | 1.7/0.7 | 4.3/2.4 | 91.4% |
| DYNG | 2468/2574 | 1.5% | 4.2/0.7 | 1.9/0.8 | 5.0/2.5 | 91.2% |
| <i>GLONASS+GPS solutions</i> | | | | | | |
| UME6 | 2349/2856 | 0.0% | 1.3/0.4 | 0.9/0.5 | 1.7/1.4 | 64.5% |
| VISO | 2403/2846 | 0.0% | 1.7/0.5 | 1.0/0.5 | 1.9/1.5 | 71.4% |
| GIGG | 2048/2874 | 0.0% | 1.9/0.5 | 1.0/0.5 | 2.1/1.5 | 70.2% |
| HOBU | 2358/2871 | 0.1% | 1.7/0.4 | 1.0/0.6 | 2.0/1.6 | 76.4% |
| USDL | 2115/2756 | 0.0% | 1.7/0.6 | 1.0/0.5 | 2.2/1.5 | 75.1% |
| SBG2 | 2178/2844 | 0.1% | 1.8/0.5 | 1.1/0.6 | 2.6/1.8 | 75.6% |
| AUTN | 2135/2821 | 0.1% | 1.8/0.5 | 1.0/0.5 | 2.3/1.6 | 74.7% |
| UNPG | 1557/2866 | 0.6% | 2.1/0.7 | 1.2/0.7 | 3.0/2.1 | 64.3% |
| TERU | 1583/2832 | 0.4% | 2.0/0.5 | 1.0/0.6 | 2.7/1.9 | 64.6% |
| DYNG | 703/2577 | 0.7% | 2.1/0.7 | 1.2/0.7 | 2.8/2.0 | 48.5% |